Detecting Stack Emissions in Infrared -"Smart" Focal Plane Arrays

What Does a Smart Array Provide?

- u The First Goal is to Extract Plumes and Laser Speckle Patterns from the Data
- Meeting these goals requires
 - Real-Time "Video" Processing for Machine Vision
 - » Concurrent Spatial and Temporal Processing
 - » Super High Bandwidth Bus Technology
 - » Ultra High Performance Digital Signal Processing

1st Step in Meeting These Requirements:

u Algorithms

- Lowpass Spatial filtering for noise reduction
- 256x256 Bandpass temporal filters (at 10 Hz to start) for motion detection
- Nonlinear spatial filter for shot noise reduction

VME System Architecture

- DataCube Image Acquisition from Infrared or CCD detector,
 Spatial Processing and Display
- CNAPS massively parallel integer DSP for Temporal Processing
- Quad TI TMS320C40 floating point DSP for Neural Processing
- mv167 Single Board Computer for Control and Timing

Data Examples:

u Raw data contains a plume which we try and extract from a complex background scene



Low Pass Filter reduces noise in image



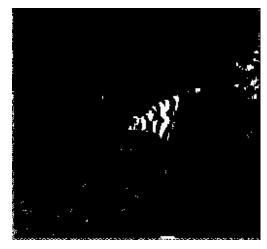
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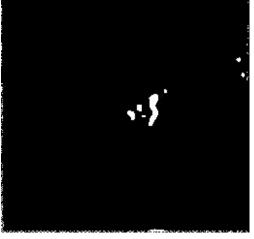
Deployable Adaptive Processing Systems

Data Examples cont:

Bandpass filtering in time extract motion but generates shot noise

Nonlinear median filter
 executed spatially reduces shot noise.





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Deployable Adaptive Processing Systems

Tools and Methods for the Future:

u Tools

- Vision ASICs will provide smarter detectors, offloading some processing
- Reconfigurable Computing Machines (FPGA's as DSPs)
 will provide 100x more DSP power
- Cross Port Switch bus technology will provide 100x more data throughput

u Methods

- Region Growing assures acquisition of entire area of interest
- Shape descriptors provide a metric of extracted Regions
- Neural Net learns which regions are interesting

Data Flow Diagram

